Investigating Selective Prediction Approaches Across Several Tasks in IID, OOD, and Adversarial Settings Neeraj Varshney, Swaroop Mishra, Chitta Baral Arizona State University, USA

Selective Prediction

Selective Prediction allows a system to abstain from answering. A system can typically abstain when its prediction is likely to be incorrect. This improves the system's **reliability**.

A Selective prediction system comprises of:

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- A **predictor** function (f) that gives the model's prediction
- A **selector** function (g) that determines if the system should output the prediction made by the predictor.

Usually, 'g' comprises of a confidence estimator ' \bar{g} ' that indicates f's prediction confidence and a threshold '*th'* that controls the abstention level:

 $\int f(x),$ if g(x) = 1

 $\alpha(m) = \mathbb{1}[\tilde{\alpha}(m)] \setminus \{h\}$

Selective Prediction Approaches

Maximum Softmax Probability (MaxProb):

- Usually, the last layer of models has a softmax activation function that gives the probability distribution P(y) over all possible answer candidates Y.
- MaxProb corresponds to the maximum softmax probability across all answer candidates.

Monte-Carlo Dropout (MCD):

• An input is inferred multiple times using different dropout masks and the outputs are aggregated to get the confidence estimate for selective prediction.

Label Smoothing (LS):

$$(f,g)(x) = \begin{cases} x \in \mathcal{F} \\ Abstain, & \text{if } g(x) = 0 \end{cases} \qquad g(x) = \mathbb{I}[g(x)] > tn \end{cases}$$

A selective prediction system makes trade-offs between **coverage** and **risk**. For a dataset D, coverage at a threshold th is defined as the fraction of total instances answered by the system (where $\bar{g} > th$) and **risk** is the error on the answered instances:

$$coverage_{th} = \frac{\sum_{x_i \in D} \mathbb{1}[\tilde{g}(x_i)) > th]}{|D|}$$
$$risk_{th} = \frac{\sum_{x_i \in D} \mathbb{1}[\tilde{g}(x_i)) > th]l_i}{\sum_{x_i \in D} \mathbb{1}[\tilde{g}(x_i)) > th]}$$

- With decrease in threshold, coverage will increase, but the risk will usually also increase.
- The overall selective prediction performance is measured by the area under Risk-Coverage curve (AUC).
- Lower the AUC, the better the selective prediction system as it ulletrepresents lower average risk across all thresholds.

- Cross-entropy loss is calculated with a weighted mixture of target labels instead of one hot 'hard' label during training.
- This prevents the network from becoming overconfident

Calibration:

A held-out dataset is annotated conditioned on the correctness of the model's predictions and a calibrator is trained over this annotated dataset to give the confidence estimate for test instances.

- **Calib C:** Held-out dataset is annotated with two classes (correct as '*positive*' class and incorrect as '*negative*' class), and calibrator is trained on this annotated binary classification dataset. Probability assigned to the positive class by this trained calibrator is used as the confidence for selective prediction.
- Calib R: Held-out dataset is annotated on a continuous scale between '0' and '1' instead of categorical labels.
- **Calib T**: A transformer-based model is trained as calibrator that leverages the entire input text for training instead of features derived from it.

Experiments and Results

In-Domain Setting

Out-of-Domain Setting

Adversarial Setting



1. None of the existing selective prediction approaches consistently and considerably outperforms *MaxProb*.

- Slight improvement in In-Domain
- Negligible improvement in Out-of-Domain
- Performance degradation in Adversarial

2. MCD requires additional computation for multiple inferences and calibration requires additional heldout dataset for training calibrator.

In contrast, MaxProb doesn't require any such additional resources and yet performs well.

3. Approaches do not translate well across tasks

MCD outperforms all other approaches on Duplicate Detection datasets but does not fare well on the NLI datasets.

